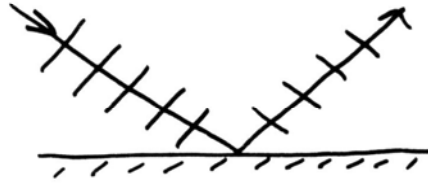


SPECKLE

Reference: Hariharan, Optical Interferometry, Ch 14.

Laser beam reflection from surfaces:

Smooth surface:



SPECULAR REFLECTION

PERFECT WAVEFRONT
(NO WAVEFRONT
DISTORTION)

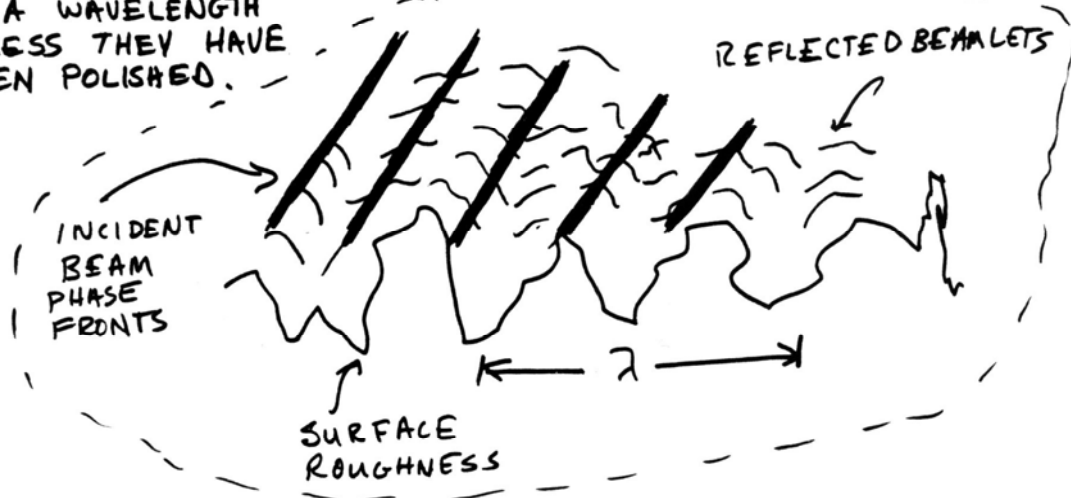
Rough surface:



NON-SPECULAR
REFLECTION

WAVEFRONT DISTORTED
BY ROUGH SURFACE

MOST SURFACES ARE
ROUGH ON THE SCALE
OF A WAVELENGTH
UNLESS THEY HAVE
BEEN POLISHED.



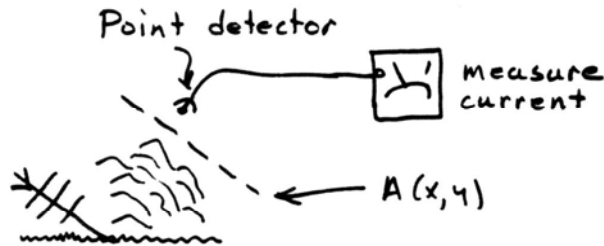
REFLECTED BEAMLETS ACT LIKE THEY COME FROM A
COLLECTION OF TINY MIRRORS ON THE SURFACE.

We assume that the reflected wavefront is the sum of the complex amplitudes of the diffracted waves from the microscopic mirrors, that is

$$A(x, y) = \frac{1}{\sqrt{N}} \sum_{m=1}^N |A_m| e^{-j\phi_m}, \quad N \text{ elements (mirrors)}.$$

If we assume that the amplitude and phase of the components are statistically independent and the range of phase shifts is equally likely between $\phi_m = 0$ to 2π , the real and imaginary parts of the complex amplitude obey gaussian statistics.

Gaussian statistics \Rightarrow The average amplitude of $A(x, y)$ is zero. Phase has uniform circular distribution.



If we take a point detector and randomly sample the irradiance in plane $A(x, y)$, we can plot a histogram of the result and get



How big are the speckles?

can look at autocorrelation of the intensity in the speckle pattern. The result is

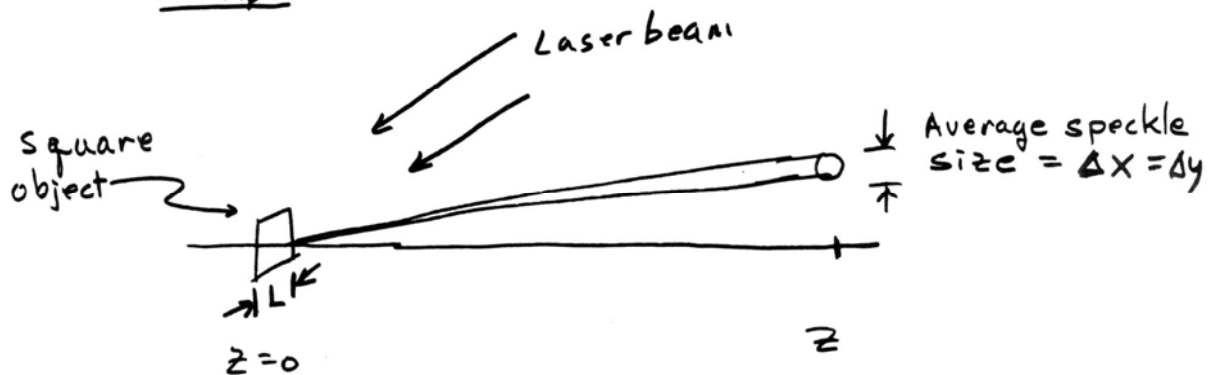
$$R_I(x_2, y_2) = \langle I \rangle^2 \left\{ 1 + \frac{\iint_{-\infty}^{\infty} |A(x_1, y_1)|^2 e^{j\frac{k}{z}(x_1 x_2 + y_1 y_2)} dx_1 dy_1}{\iint_{-\infty}^{\infty} |A(x_1, y_1)|^2 dx_1 dy_1} \right\}$$

where (x_1, y_1) are the coordinates of the plane just after the rough surface and (x_2, y_2) are the coordinates of the plane of observation. Notice that this is just a normalized Fourier transform of the size of the illuminated surface.

$$R_I(x_2, y_2) = \langle I \rangle^2 \left\{ 1 + \frac{\mathcal{F}\{|A(x_1, y_1)|^2\}}{\mathcal{F}\{|A(x_1, y_1)|^2\}_{x_2=0, y_2=0}} \right\} \begin{matrix} \xi = \frac{x_2}{\lambda z} \\ \eta = \frac{y_2}{\lambda z} \end{matrix}$$

So we can find the average size of the speckles by Fourier transforming the illuminated object.

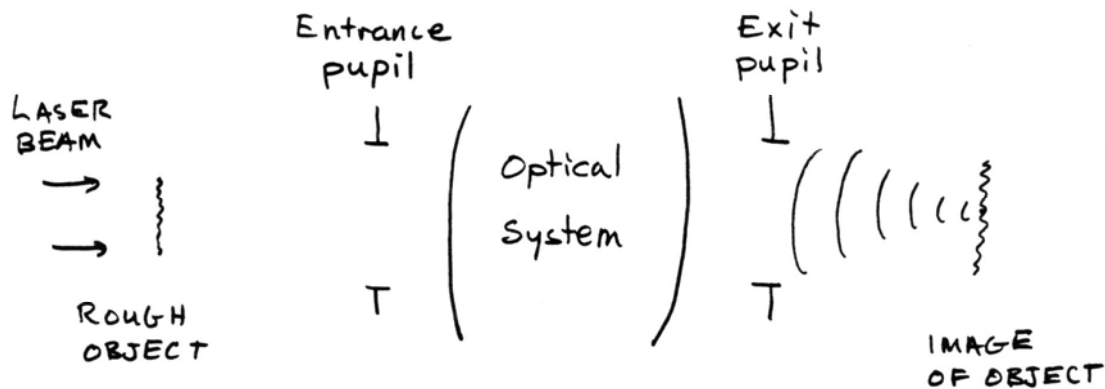
Example:



$$R_I(x_2, y_2) = \langle I \rangle^2 \left\{ 1 + \text{sinc}\left(\frac{Lx_2}{\lambda z}\right) \text{sinc}\left(\frac{Ly_2}{\lambda z}\right) \right\}$$

$\Delta x \approx$ distance to first zero in autocorrelation

$$\approx \boxed{\frac{\lambda z}{L}}$$

Speckle in optical systems:

The rough object illuminated by the laser beam forms speckle in the entrance pupil.

The exit pupil is the image of the entrance pupil, so the speckle pattern is seen in the exit pupil.

The speckle pattern is random amplitude and phase perturbations of the electric field. This is the same as the pattern in the plane just after the object. Therefore, we can treat the field in the exit pupil as originating from an object of the same size.

For a circular exit pupil of radius ρ , the average size of the speckles in the image is

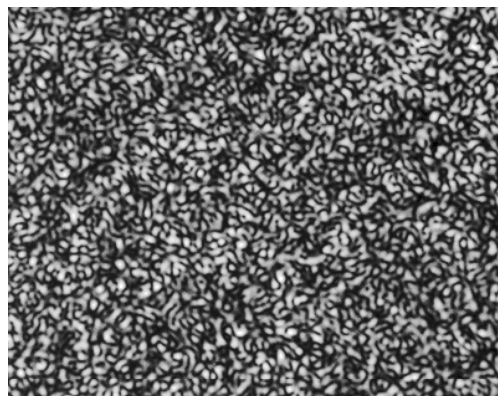
$$\Delta x = \Delta y = \boxed{\frac{0.61 \lambda f}{\rho}}$$

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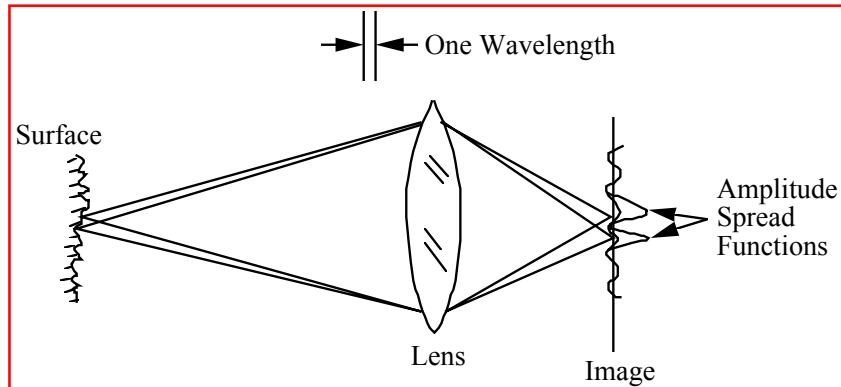
Speckle Interferometry

- **Basic Phenomena**
- **Applications**
 - Out-of-Plane Surface Vibration
 - In-Plane Displacement
 - In-Plane Vibration
 - Stellar Speckle Interferometry
- **Electronic Speckle Pattern Interferometry**

Speckle Pattern Produced by Illuminating a Rough Surface with Laser Radiation



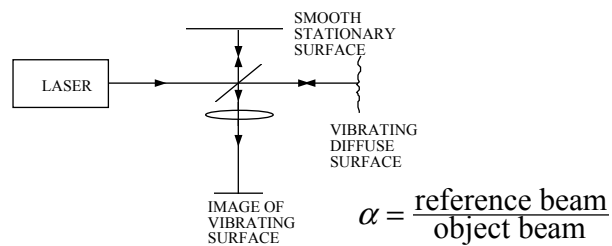
Physical Origin of Speckle for an Imaging System



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Experimental Setup for Measuring Out-of-Plane Surface Vibration



$$\text{Surface Height } z = z_0 + D \sin \omega t$$

$$\text{Speckle Contrast is } C = \frac{[1 + 2\alpha J_0^2(4\pi D / \lambda)]^{1/2}}{1 + \alpha}$$

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Speckle Contrast Reduction Due to Out-of-Plane Vibration

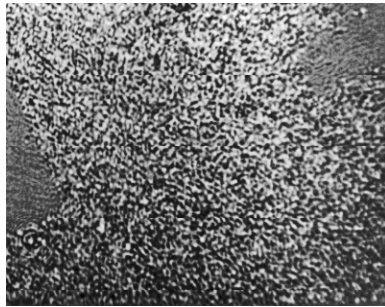


Plate Stationary

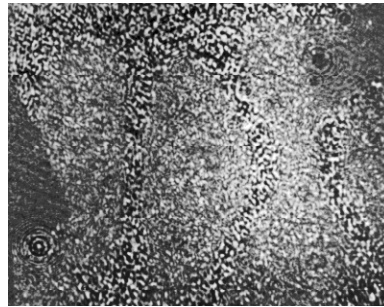
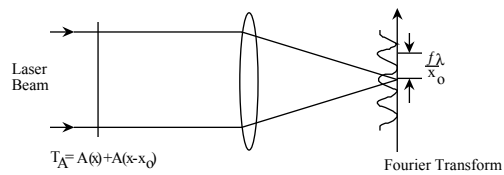
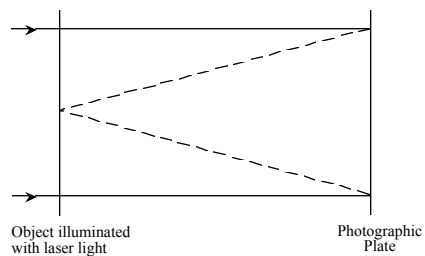


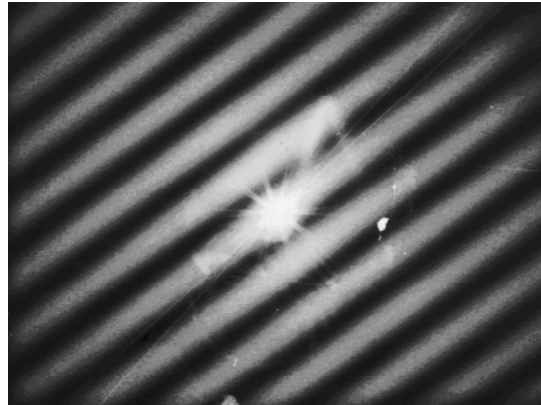
Plate Vibrating

In-Plane Displacement



Observing Young's Fringes

Young's Fringes Resulting from In-Plane Displacement



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In-Plane Vibration

- Speckle drawn into lines as surface vibrates
- Diffraction pattern gives vibration information



Linear Motion

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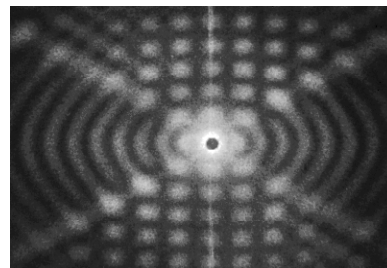


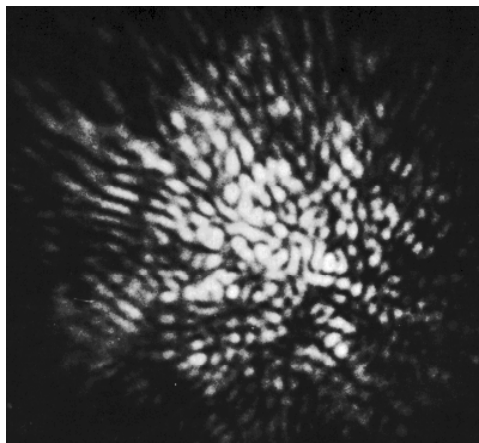
Figure-of-Eight Motion

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Stellar Speckle Interferometry

- **Atmosphere limits resolution to approximately 1 arc second (10 cm aperture)**
- **Image of star shows speckles if**
 - Exposure time less than period of atmospheric turbulence (1 msec)
 - Spectral bandwidth small (10 nm) so coherence length long
- **Speckle size determined by wavelength and telescope diameter (Diffraction-limited resolution)**
- **Speckles information limited by resolution limit of telescope, not atmospheric turbulence**

Short Exposure, Narrow Bandwidth, Photograph of Unresolved Star

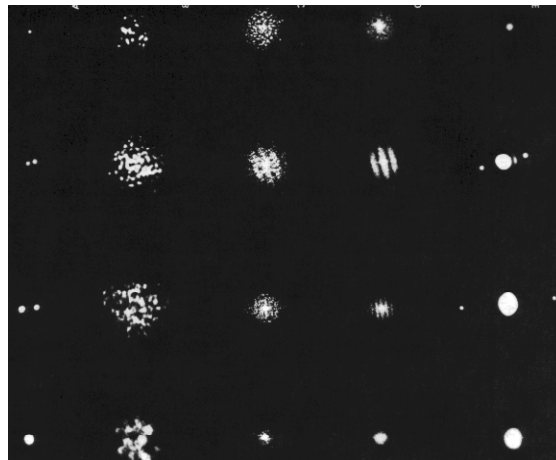


Stellar Speckle Interferometry Procedure

- Take large number, short exposure, photos of object, where each photo is taken for different realization of atmosphere
- Take Fourier transform of each photo (obtain diffraction pattern)
- Add square modulus of diffraction pattern of all photos
- Take Fourier transform of ensemble average of diffraction patterns
- Result is autocorrelation of diffraction-limited image of object

Stellar Speckle Interferometry Results

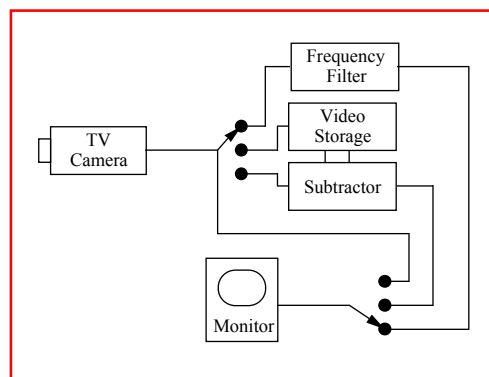
object	Photo	Fourier Transform	Sum of 20 Fourier Transforms	Fourier Transform of Sum
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Electronic Speckle Pattern Interferometry (ESPI)

- Use TV system to record speckle instead of film
- Gives real-time measurements
- Minimum speckle size limited by camera resolution
- Can perform computer analysis of speckle data

Block Diagram of Electronic Sequence of ESPI System



Examples of Time-Averaged Vibration Mode Viewing with ESPI

